

SYSTEM AND METHOD FOR MODIFYING ENGINE VALVE LIFT

CROSS-REFERENCE TO RELATED APPLICATIONS

[0001] This application is a continuation-in-part of copending U.S. Patent Application No. 10/660,508, filed on September 12, 2003, which relates to and claims priority on United States Provisional Application No. 60/409,981, filed September 12, 2002 and entitled "System and Method for Internal Exhaust Gas Recirculation," copies of which are incorporated herein by reference in their entirety.

FIELD OF THE INVENTION

[0002] The present invention relates generally to a system and method for modifying engine valve lift. In particular, the present invention relates to systems and methods for modifying engine valve lift during an engine valve event. Embodiments of the present invention may modify engine valve lift during main valve events (exhaust and/or intake), exhaust gas recirculation events, and/or during other auxiliary valve events, such as, for example, engine braking events.

BACKGROUND OF THE INVENTION

[0003] The basic principles of exhaust gas recirculation (EGR) are well known. After a properly operating engine has performed work on the combination of fuel and inlet air in its combustion chamber, the engine exhausts the remaining gas from the engine cylinder. An EGR system allows a portion of these exhaust gases to flow back into the engine cylinder.

This recirculation of gases into the engine cylinder may be used during positive power operation, and/or during engine braking cycles to provide significant benefits.

[0004] During positive power operation, an EGR system is primarily used to improve engine emissions. During engine positive power, one or more intake valves may be opened to admit fuel and air from the atmosphere, which contains the oxygen required to burn the fuel in the cylinder. The air, however, also contains a large quantity of nitrogen. The high temperature found within the engine cylinder causes the nitrogen to react with any unused oxygen and form nitrogen oxides (NO_x). Nitrogen oxides are one of the main pollutants emitted by diesel engines. The recirculated gases provided by an EGR system have already been used by the engine and contain only a small amount of oxygen. By mixing these gases with fresh air, the amount of oxygen entering the engine may be reduced and fewer nitrogen oxides may be formed. In addition, the recirculated gases may have the effect of lowering the combustion temperature in the engine cylinder below the point at which nitrogen combines with oxygen to form NO_x. As a result, EGR systems may work to reduce the amount of NO_x produced and to improve engine emissions. Current environmental standards for diesel engines, as well as proposed regulations, in the United States and other countries indicate that the need for improved emissions will only become more important in the future.

[0005] Generally, there are two types of EGR systems, internal and external. Many conventional EGR systems are external systems, which recirculate the gases from the exhaust manifold to the intake port through external piping. Many of these systems cause

exhaust gas to recirculate through the external piping by opening a normally closed EGR control valve in the piping during the intake stroke.

[0006] For example, U.S. Patent No. 5,617,726 (April 8, 1997) to Sheridan et al. and assigned to Cummins Engine Co., Inc discloses an EGR system which includes an EGR line connecting the exhaust line and intake line of the engine, cooler means for cooling the recirculated portion of the exhaust gases, a bypass line for bypassing the cooler means, and valve means for directing the flow of the recirculated portion of the exhaust gases.

[0007] U.S. Patent No. 4,147,141 (April 3, 1979) to Nagano and assigned to Toyota discloses an EGR system which includes an EGR pipe for interconnecting an exhaust pipe and an intake pipe of an engine, an EGR cooler being positioned along the EGR pipe, a bypass pipe being arranged parallel to the EGR cooler, a selection valve for controlling the flow of exhaust gas through the cooler bypass, and an EGR valve mounted on the EGR pipe for controlling the flow of exhaust gas through the EGR pipe.

[0008] Many external EGR systems require several additional components, such as, external piping, bypass lines, and related cooling mechanisms, in order for the system to operate properly. These additional components, however, may significantly increase the cost of the vehicle, and may increase the space required for the system, creating packaging and manufacturing concerns. In addition, the combination of exhaust gas and moisture in the external piping may expedite the corrosion of system components, leading to reliability issues. Various embodiments of the present invention may be simpler, less

expensive, and more reliable than many known external EGR systems that require these additional components.

[0009] Many conventional internal EGR systems provide EGR by taking exhaust gas into the combustion chamber through an open exhaust valve during the intake stroke. Without proper control, this technique may create performance problems due to the reduced amount of oxygen in the cylinder. Even though a satisfactory combustion situation may be obtained in the light-load operating range in which there is naturally an excess of air, problems may develop in the high-load operating ranges in which the proportion of air with respect to fuel is low (lean). These combustion conditions may create sub-optimal power and, in addition, may produce black smoke with large amounts of soot.

[0010] It is, therefore, desired to provide systems and methods for providing internal EGR events without the power and emissions problems associated with many conventional EGR systems. An advantage of various embodiments of the present invention is that they may provide the necessary control to avoid these pitfalls when actuating an exhaust valve during the intake stroke. In addition, various embodiments of the present invention may provide EGR by actuating one or more intake valves during the exhaust stroke.

[0011] An EGR system may also be used to optimize retarding power during engine braking operation by controlling the pressure and temperature in the exhaust manifold and engine cylinder. During engine braking, one or more exhaust valves may be selectively opened to convert, at least temporarily, the engine into an air compressor. In doing so, the engine develops retarding horsepower to help slow the vehicle down. This can provide the

operator with increased control over the vehicle and substantially reduce wear on the service brakes of the vehicle. By controlling the pressure and temperature in the engine using EGR, the level of braking may be optimized at various operating conditions.

[0012] EGR may be provided with a compression release type engine brake and/or a bleeder brake. The operation of a compression-release type engine brake, or retarder, is well known. As a piston travels upward during its compression stroke, the gases that are trapped in the cylinder are compressed. The compressed gases oppose the upward motion of the piston. During engine braking operation, as the piston approaches the top dead center (TDC), at least one exhaust valve is opened to release the compressed gases in the cylinder to the exhaust manifold, preventing the energy stored in the compressed gases from being returned to the engine on the subsequent expansion down-stroke. In doing so, the engine develops retarding power to help slow the vehicle down. An example of a prior art compression release engine brake is provided by the disclosure of the Cummins, U.S. Pat. No. 3,220,392 (November 1965), which is incorporated herein by reference.

[0013] The operation of a bleeder type engine brake has also long been known. During engine braking, in addition to the normal exhaust valve lift, the exhaust valve(s) may be held slightly open continuously throughout the remaining engine cycle (full-cycle bleeder brake) or during a portion of the cycle (partial-cycle bleeder brake). The primary difference between a partial-cycle bleeder brake and a full-cycle bleeder brake is that the former does not have exhaust valve lift during most of the intake stroke. An example of a system and method utilizing a bleeder type engine brake is provided by the disclosure of Assignee's

U.S. Pat. No. 6,594,996 (July 22, 2003), a copy of which is incorporated herein by reference.

[0014] Many known EGR systems are not useful with existing engine brake systems. Many of these systems: (1) are incompatible with compression release brakes, bleeder brakes, or both; and/or (2) require significant modifications to the existing engine in order for the EGR and braking systems to work properly together. One advantage of various embodiments of the present invention is that they may be used in conjunction with compression release braking systems and/or bleeder braking systems, and require little or no modification to the existing engine in order for the two systems to operate properly.

[0015] An EGR system may incorporate additional features to improve performance. Embodiments of the present invention may incorporate, for example, valve catch devices, valve lift clipping mechanisms, EGR lash, selective hydraulic ratios, and reset mechanisms to improve the reliability and performance of the system.

[0016] Additional advantages of the invention are set forth, in part, in the description which follows and, in part, will be apparent to one of ordinary skill in the art from the description and/or from the practice of the invention.

SUMMARY OF THE INVENTION

[0017] Responsive to the foregoing challenges, Applicant has developed innovative systems and methods for actuating one or more engine valves. In one embodiment, the present invention is a method of providing exhaust gas recirculation (EGR) in a multi-cylinder engine. The method comprises the steps of: imparting motion to a valve actuator;

actuating the engine valve of a first engine cylinder responsive to the imparted motion; determining a first and a second engine parameter level; modifying the imparted motion responsive to the level of the first engine parameter level and the second engine parameter level to produce an exhaust gas recirculation event.

[0018] It is to be understood that both the foregoing general description and the following detailed description are exemplary and explanatory only, and are not restrictive of the invention as claimed. The accompanying drawings, which are incorporated herein by reference, and which constitute a part of this specification, illustrate certain embodiments of the invention and, together with the detailed description, serve to explain the principles of the present invention.

BRIEF DESCRIPTION OF THE DRAWINGS

[0019] In order to assist the understanding of this invention, reference will now be made to the appended drawings, in which like reference numerals refer to like elements. The drawings are exemplary only, and should not be construed as limiting the invention.

[0020] Fig. 1 is a schematic representation of a valve actuation system according to a first embodiment of the present invention.

[0021] Fig. 2 is a schematic representation of a valve actuation system according to a second embodiment of the present invention.

[0022] Fig. 3 is a valve lift profile according to an embodiment of the present invention illustrating actuation of one or more engine exhaust valves during the intake stroke.

[0023] Fig. 4 is a valve lift profile according to an embodiment of the present invention

illustrating actuation of one or more engine intake valves during the exhaust stroke.

[0024] Fig. 5 is a cam that may be used in an embodiment of the present invention.

[0025] Fig. 6 is an operating schematic diagram of master and slave piston pairing according to an embodiment of the present invention.

[0026] Fig. 7 is an operating schematic diagram of master and slave piston pairing according to another embodiment of the present invention.

[0027] Fig. 8 is an exhaust gas pulse diagram and corresponding valve lift profile according to an embodiment of the present invention.

[0028] Fig. 9 is an operating schematic diagram of master and slave piston pairing according to an embodiment of the present invention for a four (4) cylinder engine.

[0029] Fig. 10 is a valve actuation system according to a third embodiment of the present invention.

[0030] Fig. 11 is a cam that may be used in conjunction with the valve actuation system shown in Fig. 10.

[0031] Fig. 12 is a valve actuation system according to a fourth embodiment of the present invention.

[0032] Fig. 13 is a first embodiment of a valve lift clipping mechanism that may be used in conjunction with the valve actuation system of the present invention.

[0033] Fig. 14 is a valve lift profile with a modified EGR valve event according to an embodiment of the present invention.

[0034] Figs. 15a and 15b illustrate a second embodiment of a valve lift clipping

mechanism that may be used in conjunction with the valve actuation system of the present invention.

[0035] Figs. 16a and 16b illustrate a third embodiment of a valve lift clipping mechanism that may be used in conjunction with the valve actuation system of the present invention.

[0036] Figs. 17a and 17b illustrate a slave piston reset mechanism that may be used in conjunction with the valve actuation system of the present invention.

[0037] Fig. 18a is a schematic diagram of a prior art valve catch assembly .

[0038] Fig. 18b is a schematic diagram of an improved means for reducing the seating velocity of an engine valve that may be used in conjunction with the valve actuation system of the present invention.

[0039] Fig. 19 illustrates a fourth embodiment of a valve lift clipping mechanism that may be used in conjunction with the valve actuation system of the present invention.

[0040] Figs. 20a and 20b illustrate a fifth embodiment of a valve lift clipping mechanism that may be used in conjunction with the valve actuation system of the present invention.

[0041] Figs. 21a and 21b illustrates a sixth embodiment of a valve lift clipping mechanism that may be used in conjunction with the valve actuation system of the present invention.

[0042] Fig. 22 illustrates a seventh embodiment of a valve lift clipping mechanism that may be used in conjunction with the valve actuation system of the present invention.

[0043] Fig. 23 illustrates an eighth embodiment of a valve lift clipping mechanism that may be used in conjunction with the valve actuation system of the present invention.

DETAILED DESCRIPTION OF PREFERRED

EMBODIMENTS OF THE INVENTION

[0044] Reference will now be made in detail to embodiments of the system and method of the present invention, examples of which are illustrated in the accompanying drawings. As embodied herein, the present invention includes systems and methods of controlling the actuation of engine valves.

[0045] A first embodiment of the present invention is shown schematically in Fig. 1 as valve actuation system **10**. The valve actuation system **10** includes a means for imparting motion **100** operatively connected to a valve actuator **300**, which in turn is operatively connected to one or more engine valves **200**. The motion imparting means **100** is adapted to apply motion to the valve actuator **300**. The valve actuator **300** may be selectively controlled to (1) transferring or (2) not transfer motion to the valves **200**. The valve actuator **300** may also be adapted to modify the amount and timing of the motion transferred to the engine valves **200**.

[0046] When operating in the motion transfer mode, the valve actuator **300** may actuate the engine valves **200** to produce an exhaust gas recirculation valve event. The valve actuator **300** may also actuate the engine valves **200** to produce other engine valve events, such as, but not limited to, main intake, main exhaust, compression release braking, and/or bleeder braking. The valve actuation system **10**, including the valve actuator **300**, may be switched between the modes of transferring motion and not transferring motion in response to a signal or input from a controller **400**. The engine valves **200** may be one or more

exhaust valves, intake valves, or auxiliary valves.

[0047] The motion imparting means **100** may comprise any combination of cam(s), push tube(s), and/or rocker arm(s), or their equivalents, adapted to impart motion to the valve actuator **300**. In at least one embodiment of the present invention, the motion imparting means **100** comprises a cam **110**. The cam **110** may comprise an exhaust cam, an intake cam, an injector cam, and/or a dedicated cam. The cam **110** may include one or more cam lobes for producing an engine valve event(s). With reference to Fig. 5, the cam **110** may include lobes, such as, for example, a main (exhaust or intake) event lobe **112**, an engine braking lobe **114**, and an EGR lobe **116**. The depictions of the lobes on the cam **110** are intended to be illustrative only, and not limiting. It is appreciated that the number, combination, size, location, and shape of the lobes may vary markedly without departing from the intended scope of the present invention.

[0048] It is further appreciated that motion imparted by the cam **110** to produce an engine valve main event may be used to provide an EGR valve event. For example, a main event (e.g., intake or exhaust) lobe **112** may be used to additionally actuate one or more valves **200** for EGR valve event. Because the full motion of the main event may provide more valve lift than required for the EGR valve event, the motion may be modified by incorporating, for example, system lash, selective hydraulic ratios between components of the valve actuator **300**, reset mechanisms, and/or valve lift clipping mechanisms.

[0049] The EGR valve event may be carried out by different valve(s) than those used to carry out the main engine valve event. These "different valves" may be of the same or

different type (intake versus exhaust) as those used for the main valve event, and may be associated with a different or the same cylinder as the valves used for the main valve event.

[0050] The valve actuator **300** may comprise any structure that connects the motion imparting means **100** to the valves **200** and is capable of selectively transmitting motion from the motion imparting means **100** to actuate the valves **200**. The valve actuator **300** may comprise, for example, a mechanical linkage, a hydraulic linkage, a hydro-mechanical linkage, an electromechanical linkage, an electromagnetic linkage, an air linkage, and/or any other linkage adapted to selectively transmit motion.

[0051] With reference to Fig. 10, when it incorporates a hydraulic circuit, the valve actuator **300** may include a master piston assembly **310** and a slave piston assembly **320**. The valve actuator **300** may be operatively connected to means for supplying hydraulic fluid to and from the actuation means **300**. The supply means may include means for adjusting the pressure of, or the amount of, fluid in the circuit, such as, for example, trigger valve(s), control valve(s), accumulator(s), check valve(s), fluid supply source(s), and/or other devices used to release hydraulic fluid from a circuit, add hydraulic fluid to a circuit, or control the flow of fluid in a circuit. The valve actuator **300** may be adapted for fixed timing (on/off) and/or variable timing. The valve actuator **300** may be located at any point in the valve train connecting the motion imparting means **100** and the valves **200**.

[0052] The controller **400** may comprise any electronic or mechanical device for communicating with the valve actuator **300** and causing it to either transfer the motion input

to it, or not transfer the motion, to the engine valves **200**. The controller **400** may include a microprocessor, linked to other engine component(s), to determine and select the appropriate operation of the valve actuator **300**. EGR may be achieved and optimized at a plurality of engine operating conditions (e.g., speeds, loads, etc.) by controlling the valve actuator **300** based upon information collected by the microprocessor from the engine component(s). The information collected may include, without limitation, engine speed, vehicle speed, oil temperature, manifold (or port) temperature, manifold (or port) pressure, cylinder temperature, cylinder pressure, particulate information, and/or crank angle.

[0053] The valve actuation system **10** may be used with any internal combustion engine. For example, the valve actuation system **10** may be used with a diesel engine, a gasoline engine, a dual fuel engine, and/or a natural gas engine. In one embodiment, as shown in Fig. 1, the valve actuation system **10** may be used with an engine that does not incorporate engine braking. Accordingly, the valve actuation system **10** may be used in conjunction with a stationary power generator, marine vehicles, agricultural vehicles and equipment, and/or any other system requiring EGR but not engine braking.

[0054] In another embodiment of the present invention, the valve actuation system **10** is adapted to provide EGR valve events in conjunction with engine braking. The valve actuation system **10** may further comprise an engine braking system **500**, as shown in Fig. 2. It is further contemplated that the valve actuator **300** may be adapted to provide engine braking in addition to providing EGR valve events.

[0055] In one embodiment of the present invention, the valve actuator **300** actuates one

or more exhaust valves to produce an EGR event **220** during the main intake event **235**, as shown in Fig. 3. A portion of the combustion gases that have been exhausted through the engine exhaust port are drawn back into the engine cylinder through the open exhaust valve by the pressure differential created by the downward movement of the piston in the engine cylinder during the intake stroke and a pressure pulse in the exhaust manifold. The recirculated gases are then combined with inlet air introduced into the engine cylinder during the intake main event.

[0056] The precise opening and closing times of the engine exhaust valve(s) (duration of the EGR event **220**) are controlled by the controller **400** and may be determined based on the pressure differential across the exhaust valve(s). The controller **400** receives input from the appropriate engine component and inputs a signal to the valve actuator **300**. In response to the signal, the valve actuator **300** may switch to the motion transfer mode and actuate the exhaust valve(s). The closing time for the valve may occur before the engine cylinder pressure is greater than the exhaust manifold pressure in order to prevent the recirculated gas from immediately escaping back into the exhaust manifold. The valve lift profile shown in Fig. 3 is for illustrative purposes only. As will be apparent to those of ordinary skill in the art, the size, shape, and timing of the EGR event **220** may vary depending on a variety of factors, including, but not limited to, the engine cylinder pressure, the exhaust manifold pressure, the lash between the valve actuator **300** and the valves **200**, the relative sizes (or hydraulic ratio) between the various components of the valve actuator **300**, and/or any other modification of the motion provided by the motion imparting

means **100**.

[0057] In another embodiment of the present invention, the valve actuator **300** actuates one or more engine intake valves to produce an EGR event **220** during the main exhaust event **215**, as shown in Fig. 4. A portion of the combustion gases are directed by the exhaust stroke from the engine cylinder (combustion chamber) through the engine intake port to the intake manifold. Some of those gases are then reintroduced into the engine cylinder with inlet air during the main intake event.

[0058] The precise opening and closing times of the engine intake valve(s) (duration of the EGR event **220**) are controlled by the controller **400** and are preferably determined based on the pressure differential across the intake valve(s). The controller **400** receives input from the appropriate engine component and inputs a signal to the valve actuator **300**.

In response to the signal, the valve actuator **300** may switch to the motion transfer mode and actuate the intake valve(s). Higher cylinder pressure (opening the intake valve for the EGR event earlier, closer to the expansion stroke) will allow more exhaust gas to be trapped in the intake port and/or manifold for recirculation, but may result in reduced expansion power (lost work). The closing time for the valve may occur before the engine cylinder pressure drops below the intake manifold pressure, to prevent the recirculated gas from immediately escaping back into the engine cylinder. The precise opening and closing times of the engine intake valve may vary depending on system requirements. The valve lift profile shown in Fig. 4 is for illustrative purposes only. As will be apparent to those of ordinary skill in the art, the size, shape, and timing of the EGR event **220** may vary

depending on a variety of factors, including, but not limited to, engine cylinder pressure, intake manifold pressure, the lash between the valve actuator **300** and the valves **200**, the relative sizes (or hydraulic ratio) between the various components of the valve actuator **300**, and/or any other modification of the motion provided by the motion imparting means **100**.

[0059] Figs. 6 and 7 depict examples of the relationships between the components of the valve actuator **300** to provide an exhaust gas recirculation valve event. In one embodiment of the present invention, as shown in Fig. 6, the master piston assembly **310** and the slave piston assembly **320** may act on engine valves associated with the same cylinder. For example, the master piston assembly **310** may receive motion from the intake cam for cylinder one (1). This motion would then be transferred to the slave piston assembly **320** for actuating an engine valve in cylinder one (1). Alternatively, the master piston assembly **310** and the slave piston assembly **320** may act relative to different cylinders, as shown in Fig. 7. For example, the master piston assembly **310** may receive motion from the intake cam for cylinder one (1). This motion would then be transferred to the slave piston assembly **320** for actuating an engine valve in cylinder three (3). It is contemplated that various embodiments of the present invention may provide any cross-cylinder actuation arrangement adapted to provide the appropriate timing of the EGR event.

[0060] Embodiments of the present invention may be adapted to utilize exhaust gas pulses produced in the exhaust manifold by one engine cylinder to facilitate the

introduction of the recirculated gas into another engine cylinder at a desired time. For example, the gas pulses may be used to introduce the recirculated gas into an engine cylinder during the main intake event. These gas pulses may be utilized in engines having split, and non-split, exhaust manifolds. Tables 1 and 2 below illustrate example operating scenarios for utilizing the exhaust gas pulses for split manifold and non-split manifold engines, respectively.

Table 1
EGR - Split Manifold

Cylinder Having EGR Event	Cylinder Providing Exhaust Gas Pulse
1	3
2	1
3	2
4	5
5	6
6	4

Table 2
EGR - Non-Split Manifold

Cylinder Having EGR Event	Cylinder Providing Exhaust Gas Pulse
1	3 & 6
2	1 & 5
3	2 & 4
4	5 & 3
5	6 & 2
6	4 & 1

[0061] Fig. 8 is a sample exhaust gas pulse diagram illustrating the pressure in the exhaust port of cylinder no. 1 for a six (6) cylinder engine with a split manifold, and a

corresponding valve lift profile for the engine valves of cylinder no. 1. If an EGR event **220** is desired during the main intake event **235**, the recirculated gas may be introduced into the engine cylinder during the crank angle range of approximately 360 degrees to approximately 500 degrees. As shown in Fig. 8, cylinder no. 3 and cylinder no. 6 provide pulses during this range. The pulse from cylinder no. 6 originates in the other bank of the split manifold, and, accordingly, does not provide the necessary pressure to drive the EGR event. The pulse from cylinder no. 3, however, provides a higher pressure than the cylinder pressure in cylinder no. 1 at that time, and, thus, facilitates the introduction of the recirculated gas into the cylinder. The exhaust ports in other cylinders may experience similar exhaust gas pulse diagrams, and may utilize the appropriate gas pulse, as shown in Table 1 above.

[0062] The motion imparted to the valve actuator **300** to produce the EGR event **220** may be modified such that the closing time for the engine valve may occur before the engine cylinder pressure is greater than the exhaust manifold pressure in order to prevent the recirculated gas from immediately escaping back into the exhaust manifold. This is illustrated by the modified EGR event **221**. The valve lift profile shown in Fig. 8 is for illustrative purposes only. As will be apparent to those of ordinary skill in the art, the size, shape, and timing of the EGR event **221** may vary depending on the means used for modifying the motion imparted to the valve actuator **300**, including, but not limited to, the lash between the valve actuator **300** and the valves **200**, the relative sizes (or hydraulic ratio) between the various components of the valve actuator **300**, the valve lift clipping

mechanism, the reset mechanism, and/or any other modification of the motion provided by the motion imparting means **100**.

[0063] For engines having non-split manifolds, the pulse from the other bank of the exhaust manifold may also have a sufficient pressure to drive the EGR event. As such, the pulse from cylinder #3 and/or cylinder #6 may be used to drive the EGR event. The exhaust ports in other cylinders in the non-split manifold may experience similar exhaust gas pulse diagrams, and may utilize the appropriate gas pulse(s), as shown in Table 2 above.

[0064] For purpose of illustration, various embodiments of the present invention will be described for use in a six (6) cylinder engine. It is contemplated, however, that various embodiments of the present invention may be used with engines having any cylinder arrangements or numbers. For example, embodiments of the present invention may be adapted for use with a four (4) cylinder engine. As discussed above in relation to a six (6) cylinder engine, embodiments of the present invention for use with a four cylinder engine may employ cross-cylinder actuation arrangements. For example, in an embodiment shown in Fig. 9, a four cylinder engine having a 1-3-4-2 firing order may have a 1-4, 2-3, 3-2, 4-1 cross-cylinder actuation arrangement.

[0065] A third embodiment of the valve actuation system **10** of the present invention will now be described with reference to Fig. 10. With reference thereto, valve actuator **300** comprises a bolt-on internal EGR system. The valve actuator **300** receives motion from the motion imparting means **100**. The motion imparting means **100** may include an intake

cam **110** having one or more cam lobes for producing an engine valve event. In one embodiment, as shown in Fig. 11, the intake cam includes a main intake event lobe **112**. As discussed above, the motion imparting means **100** may comprise any combination of cam(s), push tube(s), and/or rocker arm(s), or their equivalents, necessary to impart motion to the valve actuator **300**.

[0066] With continued reference to Fig. 10, the valve actuator **300** may comprise a master piston assembly **310** slidably disposed in a first bore **311** formed in a housing **302** such that it may slide back and forth in the bore while maintaining a hydraulic seal with the housing **302**. The valve actuator **300** may further include a slave piston assembly **320** disposed in a second bore **321** formed in the housing **302** such that it may slide back and forth in the bore while maintaining a hydraulic seal with the housing **302**. The slave piston assembly **320** is in fluid communication with the master piston assembly **310** through a hydraulic passage **304** formed in the housing **302**. The slave piston assembly **320** is disposed above a sliding pin **330**. In one embodiment, as shown in Fig. 10 an EGR lash, **Z**, exists between the slave piston assembly **320** and the sliding pin **330**. Alternatively, the slave piston assembly **320** may be in contact with the sliding pin **330**.

[0067] The valve actuator **300** is operatively connected to means **315** for supplying hydraulic fluid to the valve actuator **300**. The supply means **315** is adapted to control the supply of hydraulic fluid to and from the hydraulic passage **304**, and, correspondingly, may switch the valve actuator **300** between modes of transferring, and not transferring, the motion input from the cam **110** based on a signal received from the controller **400**. In one

embodiment, the supply means **315** comprises a fluid supply source, and one or more control valves (not shown). The one or more control valves may be selectively switched between modes of communicating, and not communicating, hydraulic fluid from the source to the hydraulic passage **304**. As discussed above, it is contemplated that the supply means **315** may include any combination of devices necessary for supplying hydraulic fluid to and from the valve actuator **300**.

[0068] The motion from the cam **110** is transferred to the master piston assembly **310**, which, in turn, transfers the motion through hydraulic pressure in the passage **304** to the slave piston assembly **320**. The hydraulic pressure causes the slave piston assembly **320** to translate in a downward direction and act on the sliding pin **330**. This, in turn, causes the sliding pin **330** to act on a single valve **200**, or on multiple valves **200** through a valve bridge **250** (as shown in Fig. 10) to produce an EGR event.

[0069] With continued reference to Fig. 10, the valve actuation system **10** may further comprise an engine braking system **500**. The engine braking system **500** may be integrated into an exhaust rocker **510**. The exhaust rocker **510** may include a central opening **505** for receipt of a rocker shaft, and a hydraulic braking passage **515** formed therein. The rocker arm **510** is adapted to pivot back and forth about the central opening **505**. The exhaust rocker **510** may further include a bore **530** for receipt of the sliding pin **330**. The braking system **500** may further include a braking piston assembly **520** disposed in a bore formed in the exhaust rocker **510**. The braking piston assembly **520** is in communication with the braking passage **515**. As will be apparent to those of ordinary skill

in the art, the engine braking system **500** may be adapted to provide compression release braking or bleeder braking based on the motion input by a motion imparting force, such as, for example, an exhaust cam (not shown).

[0070] In one embodiment, the sliding pin **330** may further comprise a rocker contact surface **334**, and a foot **336** for contacting the valve bridge **250**. As shown in Fig. 10, a braking lash, **L**, may be formed between the exhaust rocker **510** and the rocker contact surface **334**.

[0071] During engine braking, an engine braking lobe on the exhaust cam may cause hydraulic pressure to act on the braking piston assembly **520**. This, in turn, may cause the braking piston assembly **520** to act on an exhaust valve **200** through a braking pin **540**, producing an engine braking valve event. As the exhaust cam continues to rotate, the motion imparted by a main exhaust event lobe causes the exhaust rocker **510** to rotate about the central opening **505** such that the braking lash, **L**, is taken up. This causes the exhaust rocker **510** to contact the rocker contacting surface **334**, and actuate one or more engine valves **200** to produce a main exhaust event. Similarly, during positive power operation, the exhaust cam causes the exhaust rocker **510** to rotate about the central opening **505**, contact the rocker contacting surface **334**, and actuate one or more engine valves **200** to produce a main exhaust event. Accordingly, the valve actuator **300** may operate independent of the braking system **500**. In addition, the EGR lash, **Z**, may be independent of the braking lash, **L**.

[0072] The slave piston assembly **320** may include a slave piston spring **324** disposed

in the housing **302** at the base of the slave piston assembly **320**. The spring **324** biases the slave piston assembly **320** upward in the bore **321**, away from the engine valves **200**. When the exhaust rocker **510** contacts the sliding pin **330** and actuates the engine valves **200**, the slave piston assembly **320** is separated from the sliding pin **330**. The spring **324** holds the slave piston assembly **320** up against any low hydraulic pressure in the passage **304** originating from the supply means **315** that may be acting on the piston. This prevents the slave piston assembly **320** from "jacking," a condition which can cause damage to the system.

[0073] In another embodiment of the present invention, as shown in Fig. 12, the valve actuator **300** may actuate one or more intake valves **200** to produce an EGR event during a main exhaust event. In this embodiment, the motion imparting means **100** may include an exhaust cam **110** having a main exhaust lobe **112**. The slave piston assembly **320** may be adapted to act directly on single engine valve **200**, or on multiple engine valves **200** through the valve bridge **250**, as shown. Alternatively, the slave piston assembly **320** may be adapted to act on an intake rocker (not shown), causing the rocker, in turn, to actuate the valve(s) **200**.

[0074] The valve actuator **300** may further comprise means for modifying the motion input by the motion imparting means **100** in order to provide the required EGR valve event closing time. In one embodiment, as shown in Fig. 13, the valve actuator **300** further comprises a clip passage **314** formed within the master piston assembly **310**, and a check valve **312** disposed within the master piston assembly **310**. The clip passage **314** is in

communication with the master piston bore **311** and the passage **304**. An accumulator piston **350** is disposed within a bore formed in the housing **302**. When the cam **110** is at base circle, as shown in Fig. 13, the master piston assembly **310** is at its lowest position. In this position, the check valve **312** is aligned with a release passage **306** formed within the housing **302**. The opening of the clip passage **314** and the opening of the release passage **306** are separated by a variable distance X_r , as shown in Fig. 13.

[0075] The valve actuator **300** operates as described above. As the cam **110** rotates from base circle, it transfers motion to the master piston assembly **310**, which in turn transfers the motion through hydraulic pressure in the passage **304** to the slave piston assembly **320**. The hydraulic pressure causes the slave piston assembly **320** to translate in a downward direction, and act on the sliding pin **330** (if provided), which, in turn, actuates the engine valves **200**.

[0076] When the master piston assembly **310** travels a distance X_r within the bore **311**, the clip passage **314** is exposed to the release passage **306**. A portion of the hydraulic fluid in the passage **304** is now released through the release passage **306** and into an accumulator piston **350**. This reduces the pressure in the passage **304** and causes the slave piston assembly **320** to retract, under the bias of the spring **324** and the valve springs. With the slave piston assembly **320** no longer acting on the engine valves **200**, the valves close earlier. This results in a shortened, or "clipped," EGR valve event **221**, as shown by the dashed lines in Fig. 14. The valve lift profile shown in Fig. 14 is exemplary only, and it is contemplated that the exact timing of the valve closing, and, correspondingly,

the duration of the EGR event may vary. For example, the size and location of the release passage **306** may be adapted to modify the duration of the EGR valve event **221**.

[0077] When the master piston assembly **310** returns from its peak lift to its lowest position at the base circle of the cam, the check valve **312** is aligned with the release passage **306**. The fluid in the accumulator piston **350** is permitted to flow through the check valve **312**, into the master piston bore **311** and the passage **304**. Rather than releasing the fluid overboard and requiring a constant supply of fluid to the system, this arrangement promotes fluid re-use. This may reduce the need for make-up fluid for the system and may reduce “foaming” in the system fluid.

[0078] Another embodiment of the valve actuator **300** is shown with reference to Figs. 15a and 15b, in which like reference characters refer to like elements. The master piston **310** includes a check valve assembly disposed therein. The check valve assembly includes a ball **360** and a spring **362**. The spring **362** biases the ball **360** against its seat, covering a clip hole **361** formed in the master piston **310**. The spring **362** may be sized such that hydraulic pressure above the master piston **310** will not unseat the ball **360**. Alternatively, the spring **362** may be sized such that the ball **360** is unseated at a desired pressure. An annular detent **364** may be provided in the outer wall of the master piston **310**, and may be in communication with a passage **363** formed in the master piston **310**. The annular detent **364** may be in selective communication with a dump port **365**.

[0079] A clip adjustment assembly **370** may be provided above the master piston **310**. The clip adjustment assembly **370** includes a plunger **372** extending through the housing

302 into the master piston bore **311**, and a locking screw **374**. The locking screw **374** may be adjusted to extend the plunger **372** a desired distance within the bore **311**. A master piston spring **318** biases the master piston **310** away from the plunger **372**.

[0080] The embodiment of the present invention shown in Figs. 15a and 15b may be operated as follows to modify the motion input by the motion imparting means **100** in order to provide the required EGR valve event closing time. During operation, low-pressure hydraulic fluid is supplied to the passage **304**. Fluid flows through the passage **304** to the terminus of the passage at the master piston bore **311**. When the cam **110** is at base circle, the master piston **310** attains its lower most position in the master piston bore **311**. At this point, the annular detent **364** may not register with the dump port **365**. As motion is imparted to the master piston **310**, the master piston **310** moves upward within the bore **311**. The master piston motion is transferred through the hydraulic pressure in the passage **304** to the slave piston **320**. This causes the slave piston **320** to translate in a downward direction, resulting in actuation of the engine valve **200**.

[0081] With reference to Fig. 15b, as the master piston **310** continues upward translation within the master piston bore **311**, the tip of the plunger **372** contacts the ball **360** and unseats it from the clip hole **361**. At this point the annular detent **364** is registered with the dump port **365**. High pressure fluid above the master piston **310** and in the passage **304** flows through the uncovered clip hole **361** and the passage **363**, and is vented through the dump port **365**. The fluid may be dumped overboard, back to the supply means **315**, or to an accumulator.

[0082] The venting of fluid through the dump port **365** reduces the pressure in the hydraulic passage **304**, causing the slave piston **320** to retract under the bias of the spring **324** and/or the valve springs. With the slave piston **320** no longer acting on the engine valve(s) **200**, the valve(s) close earlier. With reference to Fig. 14, this results in a shortened, or clipped, EGR valve event **221**. The point **222** at which the imparted motion is modified may vary. The locking screw **374** may be loosened or tightened to adjust the position of the plunger **272** and the corresponding clip height.

[0083] In another embodiment of the present invention, the valve actuator **300** shown in Figs. 15a and 15b may be provided without the clip adjustment assembly **370**. The valve actuator **300** may include a stroke-limited slave piston assembly **320**. A stroke adjustment assembly **32** slave piston assembly **320**

[0084] Another embodiment of the valve actuator **300** is shown with reference to Figs. 16a and 16b, in which like reference characters refer to like elements. The valve actuator **300** includes a master piston sleeve **380** slidably disposed in the master piston bore **311**. A first annular detent **384** and a second annular detent **382** may be provided in the outer wall of the sleeve **380**, and a retaining groove **385** may be provided in the inner wall of the sleeve **380**. A supply passage **381** formed in the sleeve **380** is aligned with the annular detent **382**, and a clip passage **383** formed in the sleeve **380** is aligned with the annular detent **384**.

[0085] The master piston **310** is slidably disposed in a cavity **366** in the sleeve **380**. A retaining ring **387** is slidably disposed in the retaining groove **385**. A spring **386** has a first

end in contact with the sleeve **380** and a second end in contact with the retaining ring **387**. The spring **386** biases the retaining ring **387** in a downward direction against the master piston **310**.

[0086] A lash passage **388** may be provided in the housing **302**. The lash passage **388** may terminate at the top of the master piston bore **311** at a position above the passage **304**. The lash passage **388** connects to a constant low pressure hydraulic fluid supply, as shown in Fig. 16a. A check valve **389** may be disposed in the lash passage **388** so as to primarily allow only one-way fluid flow from the lash passage **388** to the master piston bore **311**.

[0087] The embodiment of the present invention shown in Fig. 16a may be operated as follows to modify the motion input by the motion imparting means **100** in order to provide the required EGR valve event closing time. The constant low pressure fluid supply biases the sleeve **380** and the master piston **310** in a downward direction in the bore **311**. Because the force of the spring **386** is greater than that produced by the low-pressure above the sleeve, the sleeve **380** and the master piston **310** move together. The sleeve **380** and the master piston **310** are biased downward until the master piston **311** contacts the motion imparting means **100**, taking up lash in the system. As shown in Fig. 16a, in this position, the annular detent **382** registers with the passage **304**, and the annular detent **384** registers with the dump port **365**.

[0088] During operation, low-pressure fluid is supplied to the passage **304**. Fluid flows through the passage **304** to the cavity **366** through the annular detent **382** and the supply

passage **381**. As motion is imparted to the master piston **310**, the master piston **310** moves upward within the cavity **366**. The fluid in the lash passage **388** above the sleeve **380** cannot escape at this point because the check valve **389** does not permit fluid to flow back towards the low pressure supply. As a result, the sleeve **380** is hydraulically locked relative to the master piston **310** and does not move.

[0089] The master piston motion is transferred through the hydraulic pressure in the passage **304** to the slave piston **320**. This causes the slave piston **320** to translate in a downward direction, resulting in actuation of the engine valve **200**. The master piston **310** continues upward translation within the master piston bore **311** until the master piston annular detent **364** registers with the sleeve annular detent **384** and the dump port **365**. High pressure fluid in the **366** and in the passage **304** flows through the clip hole **361** and the passage **363**, and is vented through the dump port **365**. The fluid may be dumped overboard, back to the low pressure supply, or to an accumulator.

[0090] The venting of fluid through the dump port **365** reduces the pressure in the hydraulic passage **304**, causing the slave piston **320** to retract under the bias of the spring **324** and/or the valve springs. With the slave piston **320** no longer acting on the engine valve(s) **200**, the valve(s) close earlier. With reference to Fig. 14, this results in a shortened, or clipped, EGR valve event **221**.

[0091] With reference to Fig. 16b, in which like reference characters refer to like elements, the valve actuator **300** provides the lash mechanism in a slightly different manner from the system shown in Fig. 16a. The lash passage **388** terminates at the

master piston bore **311** at a location above the passage **304**, but not at the top of the bore **311**. Low-pressure fluid is supplied through the lash passage **388** to a lash cavity **367** above the sleeve **380**. The fluid may slowly fill the lash cavity **367** by way of clearance between the master piston **310** and the master piston bore **311**. The fluid in the lash cavity **367** biases the sleeve **380** and the master piston **310** in a downward direction in the bore **311**, taking up lash in the system. When the system is turned off, the fluid in the cavity **367** may slowly leak out of the master piston bore **311**. The system shown in Fig. 16b may operate as described above in connection with the system shown in Fig. 16a to provide the required EGR valve event closing time.

[0092] Another embodiment of the valve actuator **300** is shown with reference to Figs. 17a and 17b, in which like reference characters refer to like elements. The valve actuator **300** may include a reset device **390** disposed in the housing **302**. The reset device **390** extends into the slave piston bore **321** above the slave piston **320**. A sealing plate **325** having a bleed hole **326** formed therein is disposed above the slave piston **320**. The slave piston **320** may include an accumulator **328** and a pressure relief hole **329** formed therein.

[0093] With reference to Fig. 17b, the reset device **390** includes a housing **391** adapted to be adjustably disposed in the housing **302**, and a reset plunger **392**. An upper spring **393** biases the reset plunger **392** in a downward direction against the sealing plate **325**. A foot of the plunger **392** covers the bleed hole **326**. A lower spring **394** rests on the housing **391**.

[0094] The embodiment of the present invention shown in Figs. 17a and 17b may be

operated as follows to modify the motion imparted to the valve actuator **300** in order to provide the required EGR valve event closing time. When the master piston **320** is on the cam base circle and no motion is being transferred to the slave piston **320**, the slave piston is biased in an upward direction against the sealing plate **325** and the reset device **390** by the slave piston spring **324**. The plunger **392** is biased against the sealing plate **325** by the upper spring **393**, covering the bleed hole **326**. As motion is imparted to the master piston **310**, the master piston **310** moves in an upward direction, and pressurizes hydraulic fluid in the passage **304**. The master piston motion is transferred through the hydraulic pressure in the passage **304** to the slave piston **320**. The hydraulic fluid enters the slave piston bore **321** and acts on the slave piston **320** and the sealing plate **325**. The hydraulic fluid may enter the space **397** between the housing **391** and the sealing plate **325** via an annular groove **396** formed in the housing **391**. As the hydraulic fluid begins to push the slave piston **320** and the sealing plate **325** downward, the plunger **392** follows under the bias of the upper spring **393**. As the plunger **392** moves down, the plunger **392** contacts the lower spring **394**. The combination of the force of the upper spring **393** and the hydraulic pressure acting on the plunger **392** is sufficient to overcome the force of the lower spring **394**. Accordingly, the foot of the plunger **392** continues to travel downward and maintain a seal with the bleed hole **326**.

[0095] The plunger **392** continues to follow the downward motion of the slave piston **320** until the plunger **392** hits a stop **395** formed in the housing **391**, and begins to separate from the sealing plate **325**. The hydraulic pressure acting on the plunger **392** is reduced.

At this point, the force of the lower spring **394** is sufficient to overcome the force of the upper spring **393** and any remaining hydraulic pressure acting on the plunger **392**. The lower spring **394** forces the plunger **392** upward to its initial position, opening the bleed hole **326**. The high-pressure fluid from the passage **304** is now dumped into the accumulator **328** through the bleed hole **326**. The combination of the accumulator **328** and the pressure relief hole **329** absorbs the motion provided by the master piston **310**. Because the high-pressure fluid is no longer acting on the slave piston **320**, the slave piston **320** retracts within the slave piston bore **321** under the bias of the slave piston spring **324** or the valve springs. With the slave piston **320** no longer acting on the engine valve(s) **200**, the valve(s) close earlier. With reference to Fig. 14, this results in a shortened EGR valve event **221**.

[0096] The accumulator **328** allows the dumped oil to be refilled back into the slave piston bore **321** through the bleed hole **326**. An annular groove formed in the sealing plate **325** may facilitate the return of fluid to the bore **321**. It is contemplated that the slave piston **310** may be provided without the accumulator, such that the high-pressure fluid dumps directly through the pressure relief hole **329**.

[0097] In alternative embodiments, the valve actuator **300** may further comprise a means for controlling the seating velocity **340** of the engine valves **200** (valve catch assembly). In one embodiment of the present invention, as shown in Fig. 18a, the valve catch assembly **340** comprises a valve catch body **341** disposed in the housing **302** above the slave piston assembly **320** such that a portion of the body **341** extends into the slave

piston bore **321**. The valve catch assembly **340** further comprises a valve catch plunger **343** disposed within the body **341**, and a valve catch spring **342** having a first end in contact with the plunger **343** and a second end in contact with the body **341**. A cross passage **344** having an orientation substantially orthogonal to the orientation of the slave piston bore **321** is formed in the valve catch plunger **343**. The cross passage **344** is in communication with the slave piston bore **321**. A bleed passage **345** having an orientation substantially parallel to the orientation of the slave piston bore **321** is formed in the valve catch plunger **343** and is in communication with the cross passage **344**. The size of the bleed passage **345** is adapted such that the flow of fluid entering the bleed passage **345** from either the plenum **322** or the slave piston bore **321** is restricted.

[0098] With continued reference to Fig. 18a, the slave piston assembly **320** may further comprise a plenum **322** formed therein. The plenum **322** is in communication with the passage **304** and the slave piston bore **321**. The plunger **343** is biased by the spring **342** into the slave piston bore **321**. The slave piston assembly **320** is biased by the slave piston spring **324** in an upward direction within the slave piston bore **321**, away from the engine valves **200**. When no fluid pressure is acting on the slave piston assembly **320**, the slave piston assembly **320** is forced against the plunger **343** because the bias of the slave piston spring **324** is greater than the spring **342**. In this position, the plunger **343** blocks the plenum **322** from communicating with the slave piston bore **321**, but places the plenum **322** in communication with the bleed passage **345**. The outer edge of the plunger **343**, in turn, is forced against the body **341**, as shown in Fig. 18a.

[0099] Operation of the valve catch assembly **340** shown in Fig. 18a will now be described. As the master piston assembly **310** is pushed up by the motion of the cam **110**, high pressure hydraulic fluid flows to the slave piston assembly **320** through the fluid passage **304** and into the plenum **322**. Because the plunger **343** may not retract into the body **341**, the slave piston assembly **320** is temporarily held against the plunger **343**. As such, the fluid flows from the plenum **322** through the bleed passage **345** and into the cross passage **344**. From the cross passage **344**, the fluid is then emptied into the slave piston bore **321**. The pressure created by the fluid in the slave piston bore **321** acts on the top of the slave piston assembly **320**, causing it to begin to translate in a downward direction. The plunger **343** follows the slave piston assembly **320** for a set distance and then separates from it. Once the slave piston assembly **320** is separated from the plunger **343**, fluid is released from the plenum **322** into the bore **321** more easily, creating additional pressure which acts on the top of the slave piston assembly **320**. The slave piston assembly **320** follows the motion of the master piston assembly **310** and translates downward in the bore **321**, causing the actuation of the engine valves **200**, as described above.

[00100] As the engine valves **200** begin to reseat, the slave piston assembly **320** moves in an upward direction within the bore **321**. The fluid in the bore flows through the passage **304** until the slave piston assembly **320** hits the plunger **343**. At this point, the continued upward translation of the slave piston assembly **320** forces the fluid in the bore **321** through the bleed passage **345** and the cross hole **344**. The small size of the bleed

passage **345**, however, restricts the flow of the hydraulic fluid leaving the bore **321**. The pressure caused by this restricted flow acts to slow down the engine valve **200** as it reseats.

[00101] Because the plunger may not retract into the body **341**, the slave piston assembly **320** may not separate from the plunger **343** until a sufficient amount of hydraulic pressure is released through the bleed passage **345** and the cross passage **344**. Because the bleed passage **345** is small relative to the plenum **322**, the pressure necessary to cause the separation may not occur immediately. Accordingly, the slave piston assembly **320** may not follow the motion of the master piston assembly **310** until a high pressure is built up in the plenum **322**. When this occurs, the high pressure may cause a very rapid initial downward displacement of the slave piston assembly **320** before the slave piston assumes the more gradual motion of the master piston assembly **310**. This uneven motion of the slave piston assembly **320** may lead to a non-smooth valve lift for the engine valve **200**.

[00102] With reference to Fig. 18b, in which like reference numerals refer to like elements from Fig. 18a, a preferred embodiment of the valve catch assembly **340** will now be described. The valve catch assembly **340** further comprises a slot **346** formed within the body **341**. The plunger **343** remains biased by the spring **342**, extending from the opening of the body **341**, however, the plunger **343** is adapted to recede into the body **341**. Thus, when no fluid pressure is acting on the slave piston assembly **320**, the slave piston assembly **320** is held directly against the body **341**. When additional pressure acts on it,

the plunger **343** may retreat into the body **341** beyond the slot **346**.

[00103] Operation of the valve catch assembly **340** shown in Fig. 18b will now be described. As described above, the motion of the master piston **310** causes high pressure hydraulic fluid to flow to the slave piston assembly **320** through the fluid passage **304** and into the plenum **322**. The high pressure flow causes the plunger to recede into the body **341** beyond the slot **346**. The high pressure flow may then act on a greater surface area of the top of the slave piston assembly **320**, leading to an earlier separation from the body **341**, and allowing the slave piston **320** to follow the initial master piston motion. This generates a smooth valve lift profile for the EGR valve event.

[00104] Another embodiment of the valve actuator **300** is shown with reference to Fig. 19, in which like reference characters refer to like elements. The valve actuator **300** includes a mechanical lash adjustment assembly **600** disposed above the master piston **310**. The lash adjustment assembly **600** may include a screw **601** extending through the housing **302** into the master piston bore **311**, and a locking nut **602**. The locking nut **602** may be adjusted to extend the screw **601** a desired distance within the bore **311**.

[00105] The adjustment of the screw **601**, in turn, adjusts the position of the master piston sleeve **380** within the bore **311**, and the position of the master piston **310**. In this manner, the lash adjustment assembly **600** may be used to adjust the position of the sleeve **380** relative to the hydraulic passage **304** and the dump port **365**, and the position of the master piston **310** relative to the motion imparting means **100**.

[00106] Another embodiment of the valve actuator **300** is shown with reference to Figs.

20a and 20b, in which like reference characters refer to like elements. The valve actuator may include the mechanical lash adjustment assembly **600** and a hydraulic lash adjustment assembly **700**. The hydraulic lash adjustment assembly **700** includes a control valve **710** and a fluid supply valve, such as, solenoid valve **720** provided in the lash passage **388**. When the solenoid valve **720** is activated, hydraulic fluid is supplied through the lash passage **388** and into the master piston bore **311** above the outer sleeve **380**. The control valve **710** may be disposed in the lash passage **380** so as to primarily allow only one-way fluid flow from the lash passage **388** to the master piston bore **311**.

[00107] The embodiment of the present invention shown in Figs. 20a and 20b may be operated as follows to modify the motion input by the motion imparting means **100** in order to provide the required valve event timing. The mechanical lash adjustment assembly **600** is adjusted such that the screw **601** extends into the bore **311**. The screw **601** contacts the outer sleeve **380**, acting against the upward biasing force of the spring **386**, and positions the outer sleeve **380** as shown in Fig. 20a. When the cam **110** is at base circle, the master piston **310** attains its lower most position in the bore **311**. The outer sleeve **380** is held up against the screw **601** by the bias of spring **386**. In this position, a gap **368** is provided between the retaining ring **387** and the master piston **310**. When a later valve closing is desired, the solenoid valve **720** is not activated, and hydraulic fluid is not supplied through the lash passage **388** to the bore **311**. As motion is imparted to the master piston **310**, the motion is transferred through the hydraulic pressure in the passage **304** to the slave piston **320**. The master piston **310** moves upward within the cavity **366** closing the gap **368**,

contacting the retaining ring **368** and compressing the spring **386**. When the annular detent **364** is registered with the dump port **365**, the high pressure fluid above the master piston **310** and in the passage **304** is vented through the dump port **365**.

[00108] When an earlier valve closing time is required, the solenoid valve **720** may be activated to permit hydraulic fluid to flow through the lash passage **388** and into the master piston bore **311**. The hydraulic pressure causes the outer sleeve **380** to travel downward within the bore **311**, and close the gap **368** between the retaining ring **387** and the master piston **310**. The control valve **710** prevents the hydraulic fluid from flowing back through the lash passage **388** from the bore **311**, locking the outer sleeve **380** in the position shown in Fig. 20b. As motion is transferred to the master piston **310**, the motion is transferred to the slave piston **320**, as described above. Because the gap **368** has been closed due to the hydraulic pressure above the outer sleeve **380**, the distance between the annular detent **364** and the dump port **365** is correspondingly reduced. As a result, the high pressure fluid above the master piston **310** and in the passage **304** is vented earlier, and accordingly, an earlier valve closing time occurs.

[00109] Another embodiment of the valve actuator **300** is shown with reference to Figs. 21a and 21b, in which like reference characters refer to like elements. The valve actuator **300** may include a spring **369** having a first end in contact with the outer sleeve **380** and a second end in contact with the master piston **310**. The spring **369** biases the master piston **310** in a direction away from the retaining ring **387**, and preferably has a lighter spring biasing force than the spring **386**. Operation of the embodiment shown in Figs. 21a and

21b is substantially the same as described above with reference to Figs. 20a and 20b. When later valve closing is required, the spring **369** may be used to help provide the gap **368**. Because the biasing force of the spring **369** is less than the biasing force of the spring **386**, the spring **369** will not affect the motion of the master piston **310** within the cavity **366**.

[00110] Another embodiment of the valve actuator **300** is shown with reference to Fig. 22, in which like reference characters refer to like elements. The embodiment shown may be operated as follows to modify the motion input by the motion imparting means **100** in order to provide the required valve event timing. When the cam **110** is at base circle, the master piston **310** attains its lower most position in the bore **311**. When a later valve closing is desired, the solenoid valve **720** is not activated, and hydraulic fluid is not supplied through the lash passage **388** to the passage **363** formed in the master piston **310**. As motion is imparted to the master piston **310**, the motion is transferred through the hydraulic pressure in the passage **304** to the slave piston **320**. The master piston **310** moves upward within the cavity **366**, causing the outer sleeve **380** to move upward within the bore **311**. When the clip passage **383** is registered with the dump port **365**, the high pressure fluid above the master piston **310** and in the passage **304** is vented through the dump port **365**. When an earlier valve closing time is required, the solenoid valve **720** may be activated to supply hydraulic fluid through the lash passage **388** and into the passage **363**. The resulting hydraulic pressure pushes the outer sleeve **380** upward within the bore **311**, reducing the distance between the clip passage **383** and the dump port **365**. As

motion is transferred to the master piston **310**, the motion is transferred to the slave piston **320**, as described above. The master piston **310** moves upward within the cavity **366**, causing the outer sleeve **380** to move upward within the bore **311**. Because the distance between the clip passage **383** and the dump port **365** has been reduced, the clip passage **383** registers with the dump port **365** at an earlier point in the valve lift profile. As a result, the high pressure fluid above the master piston **310** and in the passage **304** is vented earlier, and accordingly, an earlier valve closing time occurs.

[00111] Another embodiment of the valve actuator **300** is shown with reference to Fig. 23, in which like reference characters refer to like elements. A stroke-limited slave piston assembly **820** may be disposed in the slave piston bore **321**. The slave piston **820** includes a plunger **821** extending through the housing **302** and contacting an actuator **824**, and a locking nut **822**. The locking nut **822** may be adjusted to extend the plunger **821**, and correspondingly, the actuator **824**, a desired distance within the bore **321**. A spring **823** has a first end in contact with the actuator **824** and a second end in contact with the plunger **821**. The spring **823** biases the actuator **824** away from the plunger **821**.

[00112] The embodiment of the present invention shown in Fig. 23 may be operated as follows to modify the motion input by the motion imparting means **100** in order to provide the required valve event timing. During operation, low-pressure hydraulic fluid is supplied to the passage **304**. Fluid flows through the passage **304** to the terminus of the passage at the master piston bore **311**. When the cam **110** is at base circle, the master piston **310** attains its lower most position in the master piston bore **311**. As motion is imparted to the

master piston **310**, the master piston **310** moves upward within the bore **311**. The force of the spring **362** is greater than the hydraulic pressure above the ball **360**. As a result, the clip hole **361** remains covered, and the master piston motion is transferred through the hydraulic pressure in the passage **304** to the slave piston **320**. This causes the slave piston actuator **824** to translate in a downward direction, resulting in actuation of the engine valve **200**. As it continues to translate, the actuator **824** reaches its stroke limit and contacts the plunger **821**. Because the actuator **824** can no longer translate downward in the bore **321**, the hydraulic pressure in the passage **304** increases. The hydraulic pressure increases to a level sufficient to overcome the force of the spring **362** and unseat the ball **360**. At this point the annular detent **364** is registered with the dump port **365**. The high pressure fluid above the master piston **310** and in the passage **304** flows through the uncovered clip hole **361**, and is vented through the dump port **365**.

[00113] The venting of fluid through the dump port **365** reduces the pressure in the hydraulic passage **304**, causing the slave piston actuator **824** to retract under the bias of the spring **823**, and/or the valve springs. With the slave piston **820** no longer acting on the engine valve(s) **200**, the valve(s) close earlier. With reference to Fig. 14, this results in a shortened, or clipped, valve event **221**. The point **222** at which the imparted motion is modified may vary.

[00114] It will be apparent to those skilled in the art that variations and modifications of the present invention can be made without departing from the scope or spirit of the invention. For example, it is contemplated that embodiments of the master piston

assembly **310**, the slave piston assembly **320**, and the valve catch assembly **340** may be adapted for use together or separately. In addition, embodiments of the master piston assembly **310**, the slave piston assembly **320**, and the valve catch assembly **340** may be used in conjunction with other valve actuation systems, such as, for example, an engine braking system. Thus, it is intended that the present invention cover all such modifications and variations of the invention, provided they come within the scope of the appended claims and their equivalents.